Table 1 Comparison of measured and calculated natural frequent
--

No.	f_m	f_{51}	$\frac{100 \cdot (f_{51} - f_m)}{f_m}$	f_{30}	$\frac{100 \cdot (f_{30} - f_m)}{f_m}$	f_{20}	$\frac{100 \cdot (f_{20} - f_m)}{f_m}$
1	8.8	9.0	+2.6	9.1	+3.1	9.2	+4.0
2	30.1	30.5	+1.3	31.0	+3.0	31.3	+4.0
3	50.9	48.4	-4.9	49.7	-2.4	49.8	-2.2
4	64.5	66.3	+2.8	68.2	+5.7	69.0	+7.0
5	95.7	90.8	-5.1	94.6	-1.2	94.7	-1.0
6	110.5	121.4	+9.9	126.6	+14.5	127.5	+15.4
7	168.3	168.1	-0.1	174.4	+3.6	174.8	+3.9

af = natural frequency, Hz. Indices: m = measured; 51 = calculation with 51 assumed modes; 30 = calculation, shear-deformation deglected; 20 = calculation with bending modes only.

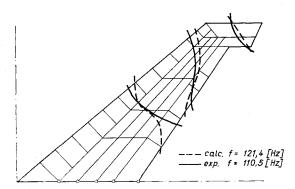


Fig. 5 The 6th mode.

was used. Twenty of the modes identify the displacement-strain relations of the plate bending theory. The components of these modes were constructed by the use of one dimensional Legendre-polynomials. Twenty-one of the modes took into account the shear deformations of the spar webs and the rib webs. These were obtained by an appropriate modification of the plate bending components. Finally, ten modes took into account the strain pattern at the discrete clamping points and may be regarded as a relaxation of the clamping effect due to the plate bending modes along the root of the fin in order to approximate the actual support conditions. These constraint modes decay quickly in spanwise direction, as would be expected from St. Venant's theory.

The fin structure was subdivided into a number of idealized elements. The skin was treated as an arrangement of plane triangles with constant thickness and the spar and rib webs were considered as tapered quadrilaterals. A two-dimensional stress pattern arising from the modes employed could be assumed in both elements. The flanges were considered as bars with linearly varying areas and axial stresses. In this context, there are no nodal points in the sense of the displacement method; however, the contours of the idealized elements can be considered as boundaries for an integration step over the volume.

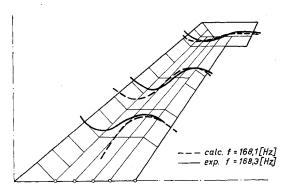


Fig. 6 The 7th mode.

To obtain the generalized stiffnesses φ_{rs} [see Eq. (1) in Ref. 1] and in an analogous manner, the generalized masses η_{rs} , the coefficients of the polynomials, and the structure data set were stored and automatically processed in an IBM 360/40 digital computer. In order to accomplish this, a suitable polynomial interpretation system was built up in FORTRAN IV language. An approximation method was developed to provide rapid integration over the volume of the structure.

Some calculated frequencies can be compared with the results of a ground resonance test in Table 1. The calculated and experimental nodal lines corresponding to the natural modes Nos. 2–7 are shown in Figs. 1–6. The calculated nodal lines stem from a computation including all 51 assumed modes. When the shear deformation modes were neglected, only natural modes (and as one can see from Table 1 also the frequencies) in excess of the fifth changed appreciably. This held true when in addition to neglecting shear deformation modes, the root constraint modes were also removed. Accordingly, the initial twenty plate bending modes remained for computation.

Reference

¹ Falkenheiner, H., "Vibration Analysis of Complex Structures Consisting of Many Members," *Journal of Aircraft*, Vol. 4, No. 6, Nov.-Dec. 1967, pp. 568-569.

Announcement: 1969 Author and Subjects Indexes

The indexes of the four AIAA archive journals (AIAA Journal, Journal of Spacecraft and Rockets, Journal of Aircraft, and Journal of Hydronautics) will be combined, as they were in 1968, and mailed separately early in 1970. Subscribers are entitled to one copy of the index for each subscription which they had in 1969. Extra copies of the index may be obtained at \$5 per copy. Please address your request for extra copies to the Circulation Department, AIAA, Room 280, 1290 Avenue of the Americas, New York, New York 10019.